# The Sixth S.M. Wu Distinguished Lecture in Manufacturing Science



From Machine Control to Manufacturing Systems Research

Yoram Koren November 17, 2011

## My Contributions are in Three Areas

1969 - 1994: C	1969 - 1994: CNC and Process Control				
E	stablishing the science base of this f	ield (70 papers; 2 books)			
In	Interpolators; control loops; adaptive control				
Тс	ool wear modeling and optimization	I met Prof. Wu in 1970 In Norway; I presented a paper on this topic.			
1979 - 1992: Robotics and Mobile Robots					
A	Algorithms for obstacle avoidance (a paper w 1200 citations)				
1:	st snake robot, 1st inflatable robot				
V	bstacle avoidance				
1994 - 2011: Reconfigurable Manufacturing Systems					
Conceiving and establishing the science base of RMS					
Optimal configurations for responsiveness					
В	Bringing science to the factory floor - systems, inspection				

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#### North American Metalworking Research Conference (NAMRC)

I met Prof. Wu in 1973 at NAMRC,

May 14-15, 1973, McMaster University, Hamilton, Canada

#### Volume 3. Statistics in Production Engineering, Grinding and Machine Tools

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#### From Sep 1974 - 1975 I was at UW, Madison



Fall 1974, Home of Prof. and Mrs. Wu, Madison

## **My Early Career**

I graduated in 1965 with B.Sc. in Electrical Engineering with concentration in Control, and decided to go to grad school.

My goal was to perform research in a field that merges theoretical research with industrial relevance.

The first Numerical Controlled (NC) machines were built in the U.S. in the late 1950s. In the late 1960's NC was an emerging interdisciplinary field.

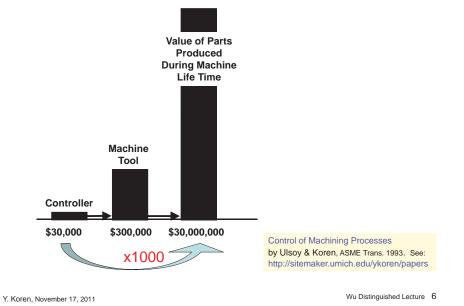
. . . Around 1970 Computerized NC (CNC) machines were introduced A scientific base for controlling NC or CNC machines did not exist; only a few researchers had an interest in this field

### Timing was perfect for CNC research

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# **The Economic Impact of Controllers**



## My Research in CNC and Process Control

Goals: 1. Part Quality: Precise parts for high-quality products

2. Productivity: The highest processing rate without violating constraints

1. Precision: -2. Productivity: Adaptive Control Interpolators **Tool Wear Modeling Control Loops** 3. Optimal locus: Cross-coupling High productivity Smart Boring subject to quality constraints

#### Research issues – Examples

- \* Coordinating motions of separately driven axes for creating precise contours
- \* Minimizing overshoots in corner cutting
- \* Maximizing productivity subject to constraints measured in real-time
- \* Optimal locus for highest productivity while maintaining constraints (e.g., surface finish)

#### Published 70 papers on these topics from 1969 to 1999

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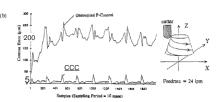
#### **Cross Coupling Control** K-axis Loop 1 Controller Controller Position Lag Erro Cross-HARDWARE Desired Coupling Contour Controller Loop 2

Y-axis

 $R_2$ Controller Controller COMPUTER

Coordinating motions of separately driven axes for creating contours

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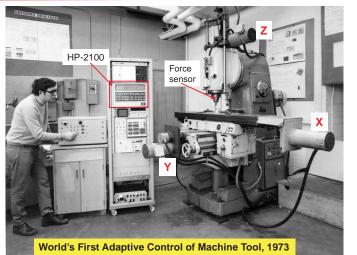


X-Axis

Actua Tool Path

Fig. 3 Contour errors and cross-coupling control (CCC) (a) Definition of the axis errors (Ex and Ey) and the contour error in the two-axis machining (b) Experimental results showing the contour error in three-dimensional conical milling for an uncoupled P-controller and the CCC

## **Adaptive Control**

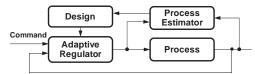


The control computer of both the CNC and the AC was Hewlett-Packard HP-2100. It was a 16-bit computer with a 4K memory, cycle time of 1 microsecond, and 16 I/O slots that were used to send signals to the three control loops and obtained signals from a sophisticated force sensor mounted on the spindle (the force sensor was designed by professor J. Tlusty).

# **Adaptive Control Optimization**

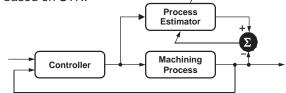
Adaptive control: A controller adapts its parameters in order to meet a given goal.

#### Self – Tuning Regulator (Karl Astrom 1973)



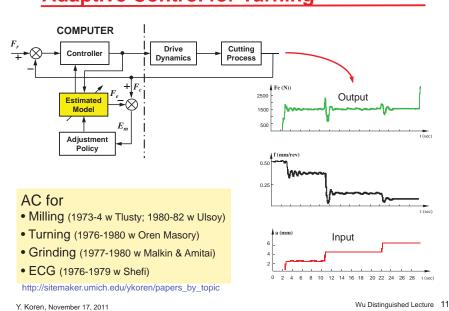
The process is known, but has unknown parameters. Parameters are estimated in real time using recursive estimation methods.

In manufacturing we developed an "Adaptive Control Optimization" that is based on STR.



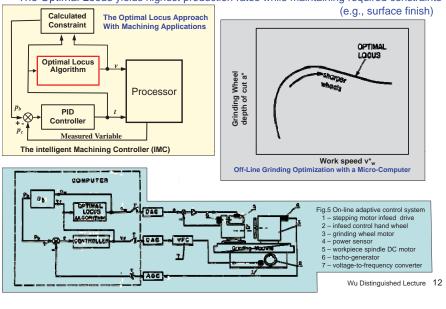
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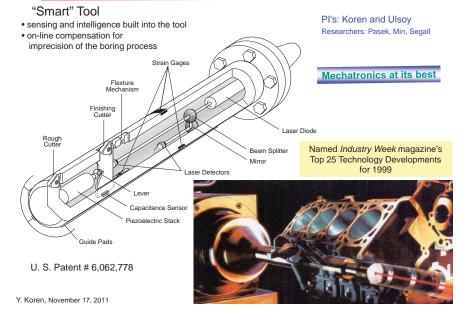
# Optimal Locus Example

The Optimal Locus yields highest production rates while maintaining required constraints



# Adaptive Control for Turning

### Smart Line Boring Station 1994-1997



## NSF-Sponsored Eng. Research Center for <u>Reconfigurable Manufacturing Systems</u>

Established on August 1, 1996

First ERC in the College of Engineering (the ERC Program started at NSF in 1984)

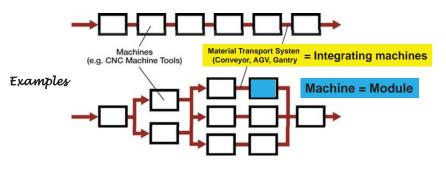
The ERC-RMS was a partnership between government, academia, and industry to identify transformative research aimed at adapting manufacturing technologies to the challenges of the 21st Century

#### Timing was good for RMS research

In 1995 the auto industry started to look for new technologies for adapting factories to globalization challenges. And, the auto industry was strong. Total support from industry during 1996 – 2009 was \$10 million According to NSF, the ERC-RMS had the largest industry support (benchmark all ERC's)

# ERC Topic: Multi-Stage Mfg. Systems

Systems are modular, and integrated by conveyors, etc.



A machining system in industry may include 120 CNC machines

How to organize a Research Center with 20 professors, 40 graduate students, 10 post-docs, 40 undergrad students and staff

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### Jacob's Dream – a Model for Visionary Research

Jacob's Dream in the Bible [Genesis Chapter 28; #12]:



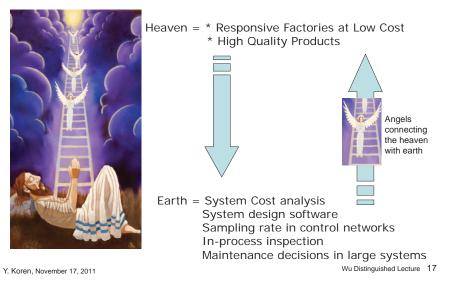
	"And Jacob dr a ladder set up	eamed that there was		
10 M	and the top of	it		
-	and the	of God were ascending		
	and descending on it."			
- AND				

Example: Prof. Wu's 2 mm project

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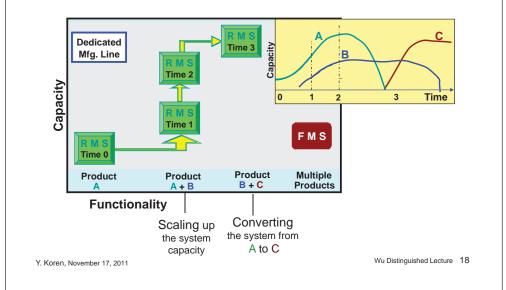
#### **RMS Strategic Research based on Jacob's Dream**

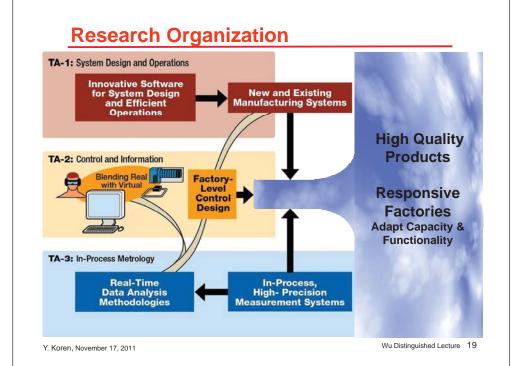
"And Jacob dreamed that there was a ladder set up <u>on the earth</u>, and the top of it reached into <u>heaven</u>, and the <u>angels</u> of God were ascending and descending on it."

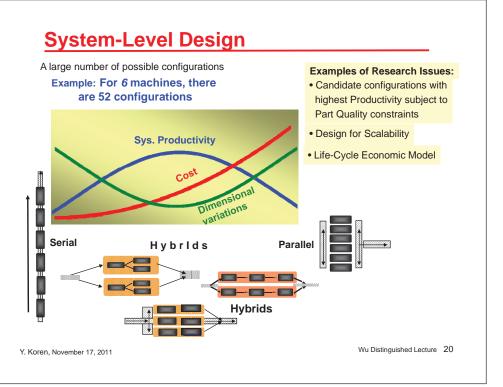


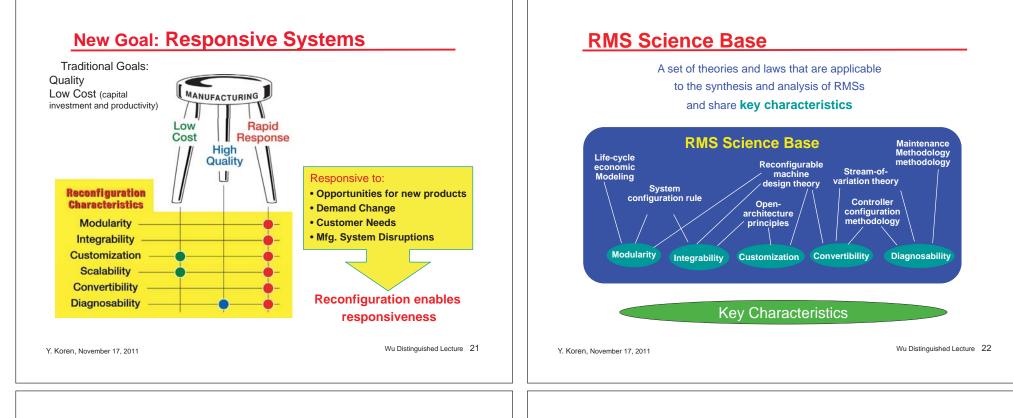
#### **Responsiveness: Adapting Capacity & Functionality**

The RMS can change in response to markets









## **Innovative Software and Hardware**

- SHARE software for automatic line balancing
- Utilized by GM

- Reconfigurable Inspection Machine (RIM)
- · Cylinder bore inspection Machine
- World-First Reconfigurable Machine Tool
- PAMS Software for Mfg. System Design, Optimization, Throughput Evaluation
- · Utilized by GM and Chrysler
- · Life-Cycle Economic modeling software
- Utilized by Ford
- · Capacity Management software for designing optimal capacity



Prototype presented at IMTS (Chicago) 2000

Reconfigurable Machine Tool Patent # 5,943750

The role of Prof. G. Spur

Fig-1

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# Tech Transfer – Example RIM

Bringing Science to the Factory Floor . . .

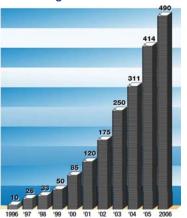


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## Impact – Creating a New Scientific Field

#### The ERC is holding 12 US Patents on:

- Reconfigurable Machine
- Reconfigurable System
- Reconfigurable Controller
- Reconfigurable Inspection Machine
- Reconfigurable Illumination for Inspection
- Reconfigurable Multi-Spindle Apparatus
- Reconfigurable Automatic Tool Changer
- Reconfigurable Power Spindle
- Integrated Reconfigurable System
- Reconfigurable Inspection for Surfaces
- Bi-Axial Co-Planar Apparatus
- Measuring Angular Alignments



Creating a new research field

Number of papers that include "Reconfigurable Manufacturing"

On 11/11/11 the number was 4111 papers

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## **Education & Outreach**

#### Create an awareness of manufacturing as a career

Research Experience for Undergraduates coming from other universities Detroit Area Pre-College Engineering Program)

Museum Project Portable Manufacturing System





Develop next generation of manufacturing leaders Systems view Multidisciplinary team work With industry Communications skills New books and teaching material

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# Future: Market-of-One Products Create Jobs

**Domestic Jobs** How to create a job?

Jobs are generated by creating something that <u>a person</u> needs



Personalized Pro Market-of-One at short delivery to.



Open-Architecture Platforms (mechanical, electrical) Applications (auto interior; rehabilitation; appliances) Product Design for Modularity Low-cost Personalized Manufacturing

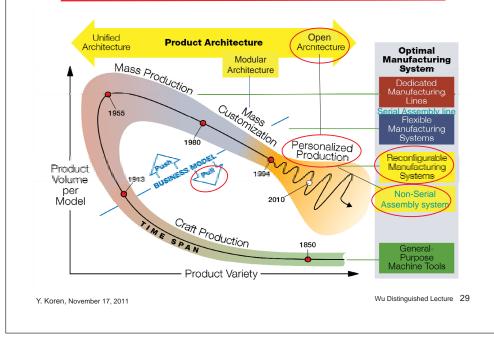
#### From the Book: "The Global Manufacturing Revolution"



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## **Paradigm Transitions Over Time**



### Conclusion of the Sixth S.M. Wu Distinguished Lecture in Manufacturing Science

"Manufacturing was, is, and shall remain the foundation of a strong economy.

No other sector can replace it.

Without a solid manufacturing base, the service and finance sectors will collapse."

